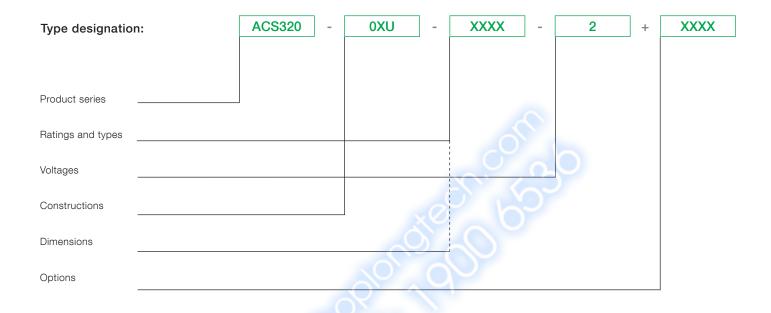


Low voltage AC drives

ABB HVAC Pump and Fan AC Drives ACS320 1.2 to 50.8 A Catalog

# Selecting and ordering your drive

Build up your own ordering code using the type designation key below or contact your local ABB drives HVAC sales office and let them know what you want. Use page 3 as a reference section for more information.



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# Introduction to ACS320 AC drives for pump and fan applications

ACS320 - XXU - XXXX - 2 + XXXX

### Making HVAC user friendly

The preprogrammed application macros and easy to use control panel make installation and drive setup simple. The control panel on the ACS320 uses HVAC terms and units, removing any guess work, and comes with 18 languages built-in. The unified height and depth of the drive frame sizes minimizes needed installation space.

### **Energy savings**

With energy savings of up to 70 percent, the ACS320 can help to attain sustainability targets. The drive's energy optimizer tunes the drive's performance to help save even more energy. Built-in energy efficiency calculators monitor the energy used and saved. The savings are shown in kilowatt-hours and in local currency. Carbon dioxide (CO2) emission reductions are also shown.

### Complete HVAC functionality

The ACS320 comes standard with four embedded communication protocols, including BACnet (MS/TP) for easy integration into building management systems. Built-in real time clock and timers help you optimize energy use. The drive provides full output current at ambient temperatures of up to 50°C without derating. Built-in software for controlling common HVAC applications includes:

- 2 PID controllers
- Timers with real time clock
- Pump and fan control
- Cooling fan control
- Pump cleaning
- Underload (broken belt) detection
- Pump protection
- Sleep function
- Pipe fill (precharge)

Typical applications for the ACS320 include:

- Supply and return fans
- Condenser fans
- Exhaust fans
- Fume hood fans
- Booster pumps
- Submersible pumps



# Typical applications

The ACS320 drive is specifically designed to meet the variable torque loads demanded by centrifugal fans and pumps. The result is maximum application uptime, reduced maintenance cost and higher energy savings.

A booster pump system is designed to boost supplied water pressure to a predetermined level in commercial buildings. The ACS320 drive features pump and fan control (PFC) for use where several parallel pumps are operated together and the required flow rate is variable.

PID control is available to allow the process to accurately maintain a pressure setpoint by adjusting the control outputs, thus allowing for precise control within difficult processes. A sleep & boost function detects slow rotation and runs the pump to boost pressure prior to shutdown. The pressure is continuously monitored and pumping restarts when the pressure falls below the minimum level.

Fan arrays use multiple motors that are often controlled by individual drives. The ACS320 offers flexibility in mounting with its compact footprint. Multiple drives in this arrangement provide redundancy ensuring year round comfort. With the optional UL type 1 kit installed on ACS320 drives the drive is plenum rated and suitable for use in the air stream. Built in building automation protocols that come standard with the product allow the user to easily set up and run the drive using BACnet, FLN, N2 or Modbus RTU reducing commission time.

Supply and return fans need to maintain air quality in spaces throughout commercial buildings, schools and hospitals. The ACS320 provides a selection of single phase 230V, three phase 230V and three phase 480V drives rated up to 30 Hp in a compact, flexible design. Whether it is cold winter nights or hot summer days, the rugged design can handle the environmental extremes with a -10 to 50 °C (14 to 122 °F) ambient temperature rating, while keeping occupants comfortable.









# Main features

ACS320 - 0XU	_	XXXX	-	2	+	XXXX
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Feature	Advantage	Benefit
Embedded Fieldbus Protocols: Modbus RTU (EIA-485); Johnson Controls N2; Siemens Building Technology FLN (P1); BACnet (MS/TP)	No need for external fieldbus options. Integrated and compact design.	Saves costs of external fieldbus devices. Increases reliability.
Pump protection functions	Integrated protection and control with preprogrammed features like pump cleaning, pipefill, inlet/outlet pressure supervision and detection of under or over load for preventive maintenance. Improves process control and system reliability. Integrates system protection.  Smoother processes: improved and optimized system. Longer life for pump and fan systems, reduced maintenance costs.	Reduces maintenance costs.  Longer life and reliable operation of pump systems.
On/off cooling fan control	Cooling fan rotates only when the drive is running, thereby cooling only when needed.	Silent operation. Improves drive's energy efficiency.
Software controlled phase inversion	Fast and easy way to change the phase order of the motor rotation.	Time savings as there is no need to change the output cable order manually.
Short parameter menu view	Only the most needed drive parameters are shown on the drive's parameter view. Complete parameter view can be changed by setting one parameter.	Time savings as the user quickly sees the most important parameters.  Fast commissioning of the drive.
Energy optimizer	Improved motor efficiency with intelligent drive control method, especially while operating on partial centrifugal loads.	Boosts energy efficiency due to lower motor currents.  Reduces audible noise from the motor.
Energy efficiency counters	Several counters to illustrate saved energy (kWh), carbon-dioxide emissions (CO <sub>2</sub> ) and cost in local currency.	Shows direct impact on energy bill and helps control operational expenditure (OPEX).
Full output current at 50 °C ambient	The drive can be operated in ambient temperatures up to 50 °C without derating the output current.	Optimized drive dimensioning for wide temperature ranges.
Load analyzer	Load analyzer saves process data, such as current and torque values, which can be used to analyze the process and dimensioning of the drive and motor.	Optimized dimensioning of the drive, motor and process.
Pump and fan control (PFC) feature to control pumps and fans in parallel	One drive controls several pumps or fans and eliminates the need for an external programmable logic controller.  Reduces motor stress and increases lifetime when auxiliary motors are driven according to the needed pump/fan capacity.  Interlock function enables one motor to be disengaged from the mains supply while others continue operating in parallel.	Saves cost of additional drives and external PLC.  Longer life for pump or fan systems while reducing maintenance time and costs.  Maintenance can be carried out safely without stopping the process.
Soft pump and fan control feature (SPFC)	Reduces unwanted pressure peaks in pumps and pipelines when an auxiliary motor is started.  Reduces inrush current to the power network while connecting new auxiliary motors.	Reduces maintenance costs.  Longer life for pump or fan systems.  Smoother processes.
PID controllers	Varies the drive's performance according to the need of the application.	Control process - pressure, flow, temperature
Compact size and flexible mounting options	The high power-to-size ratio of the drive facilitates efficient cabinet space usage.  Optimum installation layout.  Flexible installation with screw or DIN rail mounting.  Drive can be installed sideways or side-by-side.	Space savings.
User interfaces	Advanced control panel with clear alphanumerical dynamic menus, real time clock and 14 languages. Basic panel with numerical display.	Different control panels available according to functionality needs.
Maintenance assistant	Monitors consumed energy (kWh), running hours or motor rotation.	Assists in preventive maintenance of the drive, motor or run application.
Commissioning assistants	Easy setup of parameters for PID controllers, real-time clock and serial communication.	Time savings with reduced need to set the parameters manually.  Ensures all required parameters are set.
Drive protection	Motor output and I/O protected against wiring faults. Protection against unstable supply networks. Coated boards as standard.	Latest solution to protect the drive and offer trouble free use and the highest quality.

# Ratings and types

ACS320 - 0XU - XXXX - 2 + XXXX

## Type designation

This is the unique type code (shown to the below) that clearly identifies your drive by power rating and frame size. Once you have selected the type code, the frame size can be used to determine the drive dimensions, shown on the next page.

#### **Voltages**

ACS320 is available in two voltage ranges:

2 = 200 to 240 V

4 = 380 to 480 V

Insert either "2" or "4", depending on your chosen voltage, into the type designation shown above.

#### Construction

"0XU" within the type designation (shown above) varies depending on the drive phase and EMC filtering. Choose below the one you need.

01 = 1-phase

03 = 3-phase

U = EMC filter disconnected, 60 Hz frequency(In case the filter is required it can easily be connected.)

	Ratings						
Type Codes below include	Power	In	put		Output		
Blank Panel only	Nominal Horsepower	Nominal without Reactor	Nominal with 5% Reactor	Continous @ 50C, 10% Overload <sup>1</sup>	Continous @ 40C, 0% Overload		
1-phase supply voltage 200	- 240 V units (Confi	irm output ratings	s meet motor requ	irements)			
ACS320-01U-02A4-2	0.5	6.1	N/A	2.3	2.4	R0	
ACS320-01U-04A7-2	1	11.4	N/A	4.5	4.7	R1	
ACS320-01U-06A7-2	1.5	16.1	N/A	6.5	6.7	R1	
ACS320-01U-07A5-2	2	16.8	N/A	7.2	7.5	R2	
ACS320-01U-09A8-2	3	21.0	N/A	9.4	9.8	R2	
3-phase supply voltage 200	- 240 V units						
ACS320-03U-02A6-2	0.5	4.7	2.6	2.4	2.6	R0	
ACS320-03U-03A9-2	0.75	6.7	3.9	3.5	3.9	R0	
ACS320-03U-05A2-2	1	8.4	5.2	4.7	5.2	R1	
ACS320-03U-07A4-2	1.5	13.0	7.4	6.7	7.4	R1	
ACS320-03U-08A3-2	2	13.2	8.3	7.5	8.3	R1	
ACS320-03U-10A8-2	2+	15.7	10.8	9.8	10.8	R2	
ACS320-03U-14A6-2	3	23.9	14.6	13.3	14.6	R2	
ACS320-03U-19A4-2	5	27.3	19.4	17.6	19.4	R2	
ACS320-03U-26A8-2	7.5	45	26.8	24.4	26.8	R3	
ACS320-03U-34A1-2	10	55	34.1	31.0	34.1	R4	
ACS320-03U-50A8-2	15	76	50.8	46.2	50.8	R4	
3-phase supply voltage 380	- 480 V units					•	
ACS320-03U-01A2-4	0.5	2.2	1.2	1.1	1.2	R0	
ACS320-03U-01A9-4	0.75	3.6	1.9	1.7	1.9	R0	
ACS320-03U-02A4-4	1	4.1	2.4	2.2	2.4	R1	
ACS320-03U-03A3-4	1.5	6.0	3.3	3.0	3.3	R1	
ACS320-03U-04A1-4	2	6.9	4.1	3.7	4.1	R1	
ACS320-03U-05A6-4	3	9.6	5.6	5.1	5.6	R1	
ACS320-03U-07A3-4	3+	11.6	7.3	6.6	7.3	R1	
ACS320-03U-08A8-4	5	13.6	8.8	8.0	8.8	R1	
ACS320-03U-12A5-4	7.5	18.8	12.5	11.4	12.5	R3	
ACS320-03U-15A6-4	10	22.1	15.6	14.2	15.6	R3	
ACS320-03U-23A1-4	15	30.9	23.1	21.0	23.1	R3	
ACS320-03U-31A0-4	20	52.0	31.0	28.2	31	R4	
ACS320-03U-38A0-4	25	61.0	38.0	34.5	38	R4	
ACS320-03U-44A0-4	30	67.0	44.0	40.0	44	R4	

<sup>1)</sup> Overloadability for one minute every ten minutes.

# Technical data

ACS320 - 0XU - XXXX - 2 + XXXX

	and the second s
Voltage and power range	1-phase, 200 to 240 V $\pm$ 10% 2.4 to 9.8 A ( $I_{2N}$ ) 3-phase, 200 to 240 V $\pm$ 10% 2.6 to 50.8 A ( $I_{2N}$ ) 3-phase, 380 to 480 V $\pm$ 10% 1.2 to 44.0 A ( $I_{2N}$ )
Frequency	48 to 63 Hz
Motor connection	
Voltage Frequency Continuous loading	3-phase, from 0 to U <sub>supply</sub> 0 to 500 Hz  I <sub>2N</sub> maximum continuous output current at
capability	ambient temperature of +40 °C.  No overloadability, derating 1% for every additional 1 °C up to 50 °C.  I <sub>LD</sub> continuous output current at max ambient temperature of +50 °C.  10% overloadability for one minute every ten minutes.
Switching frequency	
Default	4 kHz
Selectable	4 to 16 kHz with 4 kHz steps
Acceleration time	0.1 to 1800 s
Deceleration time	0.1 to 1800 s
Motor control method	Scalar U/f
Environmental limits	
Ambient temperature	-10 to 50 °C (14 to 122 °F), no frost
A 1 · · · 1	allowed
Altitude Output current	Rated current available at 0 to 1000 m
Output Current	(0 to 3281 ft) reduced by 1% per 100 m
	(328 ft) over 1000 to 2000 m
	(3281 to 6562 ft)
Relative humidity	Lower than 95% (without condensation)
Degree of protection	IP20/optional NEMA 1 enclosure
Enclosure colour	NCS 1502-Y, RAL 9002, PMS 420 C
Contamination levels	IEC721-3-3
Transportation	No conductive dust allowed Class 1C2 (chemical gases)
Storage	Class 1S2 (solid particles) Class 2C2 (chemical gases)
otorago	Class 2S2 (solid particles)
Operation	Class 2S2 (solid particles) Class 3C2 (chemical gases) Class 3S2 (solid particles)

### Product compliance

Low Voltage Directive 2006/95/EC
Machinery Directive 2006/42/EC
EMC Directive 2004/108/EC
Quality assurance system ISO 9001
Environmental system ISO 14001
UL, cUL, CE, C-Tick and GOST R approvals
RoHS compliant

Programmable control connections           Two analog inputs           Voltage signal           Unipolar         0 (2) to 10 V, $R_{in} > 312 k\Omega$ Bipolar         -10 to 10 V, $R_{in} > 312 k\Omega$ Current signal         0 (4) to 20 mA, $R_{in} = 100 \Omega$ Unipolar         20 to 20 mA, $R_{in} = 100 \Omega$ Bipolar         -20 to 20 mA, $R_{in} = 100 \Omega$ Resolution         0.1%           Accuracy         ± 1%           One analog output         0 (4) to 20 mA, $R_{in} = 100 \Omega$ Auxiliary voltage         24 V DC ± 10%, max. 200 mA           Five digital inputs         12 to 24 V DC with internal or external supply, PNP and NPN, pulse train           0 to 16 kHz         2.4 kΩ           Input impedance         0.4 kΩ           One relay output         NO + NC           Maximum switching voltage         NO + NC           Maximum switching current         0.5 A/30 V DC, short circuit           Trequency         Transistor output           Maximum switching current         100 mA/30 V DC, short circuit           Trequency         1.2 to 16 kHz           Resolution         1.2 to 16 kHz           Accuracy         2.9%           Serial communication         Daisy-chained bus, w		
$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	Programmable control conne	ections
$\begin{array}{llllllllllllllllllllllllllllllllllll$	Two analog inputs	
Bipolar Current signal       -10 to 10 V, $R_{in} > 312 kΩ$ Current signal       0 (4) to 20 mA, $R_{in} = 100 Ω$ Bipolar Resolution Accuracy       -20 to 20 mA, $R_{in} = 100 Ω$ Accuracy       ± 1%         One analog output Auxiliary voltage       24 V DC ± 10%, max. 200 mA         Five digital inputs       12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz         Input impedance       2.4 kΩ         One relay output Type       NO + NC         Maximum switching voltage Maximum switching current Type       NO + NC         Maximum switching voltage Maximum switching current Frequency       Transistor output 30 V DC         Maximum switching current Frequency       10 Hz to 16 kHz         Hz to 16 kHz       1 Hz         Accuracy       1.2 to 16 kHz         1 Hz to 16 kHz       1 Hz         Accuracy       0.2%         Serial communication       Shielded twisted pair, impedance 100 to 150 ohms         Termination Isolation       Daisy-chained bus, without dropout lines         Bus interface isolated from drive       1.2 to 76.8 kbit/s         Serial, asynchronous, half duplex         Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)         Chokes         AC input chokes		
Current signal Unipolar $0 (4)$ to $20 \text{ mA}$ , $R_{\text{in}} = 100 \Omega$ $\Omega$ Bipolar $-20 \text{ to } 20 \text{ mA}$ , $R_{\text{in}} = 100 \Omega$ $\Omega$ Resolution $0.1\%$ $\Omega$ Correctly $0 (4)$ to $20 \text{ mA}$ , $\Omega$	•	
Unipolar Bipolar $0 (4) \text{ to } 20 \text{ mA}, R_{\text{in}} = 100 \ \Omega$ $-20 \text{ to } 20 \text{ mA}, R_{\text{in}} = 100 \ \Omega$ $0.1\%$ Accuracy $\pm 1\%$ $0.1\%$ Accuracy $\pm 1\%$ $0.1\%$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 500 \ \Omega$ Auxiliary voltage $0 (4) \text{ to } 20 \text{ mA}, \log 4 < 100 \ \Omega$ Along the internal or external supply, PNP and NPN, pulse train $0 \text{ to } 16 \text{ kHz}$ $0 \text{ to } 16 \text{ to } 16 \text{ to } 16 \text{ kHz}$ $0 \text{ to } 16 $	'	-10 to 10 V, $R_{in}$ > 312 k $\Omega$
Bipolar       -20 to 20 mA, R <sub>in</sub> = 100 Ω         Resolution       0.1%         Accuracy       ± 1%         One analog output       0 (4) to 20 mA, load < 500 Ω         Auxiliary voltage       24 V DC ± 10%, max. 200 mA         Five digital inputs       12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz         Input impedance       2.4 kΩ         One relay output       NO ± NC         Maximum switching voltage       NO ± NC         Maximum switching current       250 V AC/30 V DC         Maximum switching voltage       NO ± NC         Maximum switching voltage       Transistor output         Maximum switching voltage       Transistor output         Maximum switching current       100 mA/30 V DC, short circuit         Frequency       10 Hz to 16 kHz         Resolution       1 Hz         Accuracy       2.2%         Serial communication       Shielded twisted pair, impedance 100 to 150 ohms         Termination       Bus interface isolated from drive         Isolation       1.2 to 76.8 kbit/s         Serial, asynchronous, half duplex         Modbus RTU (EIA-485);         Johnson Controls N2;         SiemensBuilding Technology FLN (P1);         BACnet (MS/TP) <th>•</th> <th></th>	•	
Resolution       0.1%         Accuracy       ± 1%         One analog output       0 (4) to 20 mA, load < 500 Ω         Auxiliary voltage       24 V DC ± 10%, max. 200 mA         Five digital inputs       12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz         Input impedance       2.4 kΩ         One relay output       NO + NC         Maximum switching voltage       NO + NC         Maximum switching current       Maximum switching current         Maximum switching voltage       Transistor output         Maximum switching current       100 mA/30 V DC, short circuit         Frequency       10 Hz to 16 kHz         Resolution       1 Hz         Accuracy       0.2%         Serial communication       Daisy-chained bus, without dropout lines         Isolation       Bus interface isolated from drive         Transfer rate       1.2 to 76.8 kbit/s         Communication type       Serial, asynchronous, half duplex         Protocol       Modbus RTU (EIA-485);         Johnson Controls N2;       SiemensBuilding Technology FLN (P1);         BACnet (MS/TP)       External option         For reducing THD in partial loads and to	•	
Accuracy ± 1% One analog output 0 (4) to 20 mA, load < 500 Ω Auxiliary voltage 24 V DC ± 10%, max. 200 mA Five digital inputs 12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz 2.4 kΩ One relay output Type NO + NC Maximum switching voltage Maximum switching current Maximum continuous current Type Transistor output 30 V DC, 5 A/230 V AC Maximum switching voltage Maximum switching current Prequency 10 Hz to 16 kHz Frequency 10 Hz to 16 kHz Accuracy 0.2%  Serial communication  Cable Shielded twisted pair, impedance 100 to 150 ohms Termination Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Communication type Protocol Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes External option For reducing THD in partial loads and to	•	1 77
One analog output       0 (4) to 20 mA, load < 500 Ω         Auxiliary voltage       24 V DC ± 10%, max. 200 mA         Five digital inputs       12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz         Input impedance       2.4 kΩ         One relay output       NO + NC         Maximum switching voltage       NO + NC         Maximum switching current       250 V AC/30 V DC         Maximum switching current       0.5 A/30 V DC; 5 A/230 V AC         Maximum switching voltage       30 V DC         Maximum switching current       10 mA/30 V DC, short circuit         Frequency       10 Hz to 16 kHz         Resolution       1 Hz         Accuracy       0.2%         Serial communication       Daisy-chained bus, without dropout lines         Bus interface isolated from drive       1.2 to 76.8 kbit/s         Communication type       Serial, asynchronous, half duplex         Protocol       Modbus RTU (EIA-485);         Johnson Controls N2;       SiemensBuilding Technology FLN (P1);         BACnet (MS/TP)         Chokes         AC input chokes       External option         For reducing THD in partial loads and to		
Auxiliary voltage       24 V DC ± 10%, max. 200 mA         Five digital inputs       12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz         Input impedance       2.4 kΩ         One relay output       NO + NC         Maximum switching voltage       NO + NC         Maximum switching current       250 V AC/30 V DC         Maximum continuous current       0.5 A/30 V DC; 5 A/230 V AC         Maximum switching voltage       30 V DC         Maximum switching current       100 mA/30 V DC, short circuit         Frequency       10 Hz to 16 kHz         Resolution       1 Hz         Accuracy       0.2%         Serial communication       Shielded twisted pair, impedance 100 to 150 ohms         Termination       Daisy-chained bus, without dropout lines         Isolation       Bus interface isolated from drive         Transfer rate       1.2 to 76.8 kbit/s         Communication type       Serial, asynchronous, half duplex         Modbus RTU (EIA-485);       Johnson Controls N2;         SiemensBuilding Technology FLN (P1);       BACnet (MS/TP)         Chokes         AC input chokes       External option         For reducing THD in partial loads and to		
Five digital inputs  12 to 24 V DC with internal or external supply, PNP and NPN, pulse train 0 to 16 kHz 2.4 kΩ  One relay output Type Maximum switching voltage Maximum continuous current Maximum switching voltage Maximum switching current Type Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms Termination Isolation Transfer rate Communication type Protocol  Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	One analog output	
supply, PNP and NPN, pulse train 0 to 16 kHz 2.4 kΩ  One relay output Type Maximum switching voltage Maximum switching current Maximum continuous current Type Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching current Type Maximum switching voltage Maximum switching current Transistor output 30 V DC Maximum switching current Transistor output 100 mA/30 V DC, short circuit Frequency Resolution 1 Hz 0.2%  Serial communication  Cable Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s  Communication type Protocol Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Auxiliary voltage	24 V DC ± 10%, max. 200 mA
Input impedance  One relay output Type  Maximum switching voltage Maximum switching current Maximum continuous current Type  Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching current Type  Maximum switching current Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz Accuracy 0.2%  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Five digital inputs	12 to 24 V DC with internal or external
Input impedance  One relay output Type  Maximum switching voltage Maximum continuous current  One digital output Type  Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching current Type  Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  India voltage Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  AC input chokes  Ac input chokes  NO + NC 250 V AC/30 V DC 0.5 A/230 V AC 250 V AC/30 V DC 0.5 A/230 V AC 250 V AC/30 V DC 0.5 A/230 V AC 250 V AC/30 V DC 0.5 A/230 V AC 26 A rms  NO + NC 250 V AC/30 V DC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No + NC 0.5 A/230 V AC 26 A rms  No Hotion 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2% 10 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2% 10 mA/30 V DC, short circuit 10 to 150 ches 10 mA/30 V DC, short circuit 10 mA/30 V DC 10 mA/30 V DC 10 mA/30		supply, PNP and NPN, pulse train
One relay output Type Maximum switching voltage Maximum switching current Maximum continuous current One digital output Type Maximum switching voltage Maximum switching voltage Maximum switching voltage Maximum switching current Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Cable Shielded twisted pair, impedance 100 to 150 ohms Termination Isolation Transfer rate Communication type Protocol  Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		0 to 16 kHz
Type Maximum switching voltage Maximum switching current Maximum continuous current  One digital output Type Maximum switching voltage Maximum switching voltage Maximum switching current Maximum switching current  Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  NO + NC 250 V AC/30 V DC 0.5 A/230 V AC 2 A rms  Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Input impedance	2.4 kΩ
Maximum switching voltage Maximum switching current Maximum continuous current  One digital output Type Maximum switching voltage Maximum switching voltage Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Tamsistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	One relay output	
Maximum switching current Maximum continuous current  One digital output Type  Maximum switching voltage Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Tamsistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Туре	NO + NC
Maximum continuous current  One digital output Type  Maximum switching voltage Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  Maximum switching current  Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Maximum switching voltage	250 V AC/30 V DC
Transistor output Type Maximum switching voltage Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  Chokes  AC input chokes  Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 Hz 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 Hz 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 Hz 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 10 Hz 10	Maximum switching current	0.5 A/30 V DC; 5 A/230 V AC
Type Maximum switching voltage Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Transistor output 30 V DC 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 1 Hz 0.2%  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s  Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Maximum continuous current	2 A rms
Maximum switching voltage  Maximum switching current  Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  Chokes  AC input chokes  Maximum switching voltage Auximum switching current Auximum switching voltage Auximum switching current Auximum switching voltage Auximum switching volt	One digital output	
Maximum switching current Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation Transfer rate Communication type Protocol  Protocol  Chokes  AC input chokes  Tin Hz 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 11 Hz 100 mA/30 V DC, short circuit 10 Hz to 16 kHz 12 to 76 kHz 150 ohms 150 o	Туре	Transistor output
Frequency Resolution Accuracy  Serial communication  Cable  Termination Isolation  Transfer rate Communication type Protocol  Chokes  AC input chokes  AC input chokes  10 Hz to 16 kHz 1 Hz 20.2%  Shielded twisted pair, impedance 100 to 150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  External option For reducing THD in partial loads and to	Maximum switching voltage	
Resolution Accuracy  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms  Termination Isolation  Transfer rate  Communication type Protocol  Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Maximum switching current	
Accuracy  Serial communication  Cable  Shielded twisted pair, impedance 100 to 150 ohms  Termination  Isolation  Transfer rate  Communication type  Protocol  Daisy-chained bus, without dropout lines  Bus interface isolated from drive  1.2 to 76.8 kbit/s  Serial, asynchronous, half duplex  Modbus RTU (EIA-485);  Johnson Controls N2;  SiemensBuilding Technology FLN (P1);  BACnet (MS/TP)  Chokes  AC input chokes  External option  For reducing THD in partial loads and to		
Serial communication  Cable Shielded twisted pair, impedance 100 to 150 ohms  Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s  Communication type Protocol Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		i
Cable  Shielded twisted pair, impedance 100 to 150 ohms  Daisy-chained bus, without dropout lines  Bus interface isolated from drive  1.2 to 76.8 kbit/s  Communication type  Protocol  Modbus RTU (EIA-485);  Johnson Controls N2;  SiemensBuilding Technology FLN (P1);  BACnet (MS/TP)  Chokes  AC input chokes  External option  For reducing THD in partial loads and to		0.2%
Termination Isolation Transfer rate Communication type Protocol  Chokes  AC input chokes  Termination  150 ohms Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  External option For reducing THD in partial loads and to	Serial communication	,
Termination Isolation Bus interface isolated from drive Transfer rate Communication type Protocol  Chokes  AC input chokes  Daisy-chained bus, without dropout lines Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  External option For reducing THD in partial loads and to	Cable	
Isolation Transfer rate Communication type Protocol  Chokes  AC input chokes  Bus interface isolated from drive 1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  External option For reducing THD in partial loads and to	Termination	
Transfer rate Communication type Protocol  1.2 to 76.8 kbit/s Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		
Communication type Protocol  Serial, asynchronous, half duplex Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		
Protocol  Modbus RTU (EIA-485); Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	Communication type	Serial, asynchronous, half duplex
Johnson Controls N2; SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to	* '	
SiemensBuilding Technology FLN (P1); BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		· · · · · · · · · · · · · · · · · · ·
BACnet (MS/TP)  Chokes  AC input chokes  External option For reducing THD in partial loads and to		· ·
Chokes  AC input chokes  External option For reducing THD in partial loads and to		SiemensBuilding Technology FLN (P1);
AC input chokes External option For reducing THD in partial loads and to		BACnet (MS/TP)
For reducing THD in partial loads and to	Chokes	
	AC input chokes	External option
comply with EN/IEC 61000-3-12		For reducing THD in partial loads and to
Comply with ENVICO 01000 0 12		comply with EN/IEC 61000-3-12
AC output chokes External option	AC output chokes	External option
To achieve longer motor cables		To achieve longer motor cables

# Dimensions and weights

ACS320

0XU

XXXX

2

XXXX

## Cabinet-mounted drives (IP20 UL open)

Frame size	IP20 UL open								
	H1	H2	Н3	W	D	Weight			
	in	in	in	in	in	lb			
R0	6.65	7.95	9.41	2.76	6.34	2.6			
R1	6.65	7.95	9.41	2.76	6.34	2.6			
R2	6.65	7.95	9.41	4.13	6.5	3.3			
R3	6.65	7.95	9.29	6.65	6.65	5.5			
R4	7.13	7.95	9.61	10.24	6.65	9.7			

H1 = Height without fastenings and clamping plate

H2 = Height with fastenings but without clamping plate

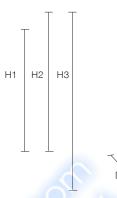
H3 = Height with fastenings and clamping plate

H4 = Height with fastenings and NEMA 1 connection box

H5 = Height with fastenings, NEMA 1 connection box and hood

W = Width

D = Depth





### Wall-mounted drives (NEMA 1)

Frame size	NEMA 1									
	H4	H4 H5 V		D	Weight					
	in	in	in	in	lb					
R0	10.12	11.02	2.76	6.65	3.5					
R1	10.12	11.02	2.76	6.65	3.5					
R2	10.12	11.10	4.13	6.65	4.2					
R3	10.24	11.77	6.65	6.97	6.8					
R4	10.63	12.60	10.24	6.97	11.0					

H4 = Height with fastenings and NEMA 1 connection box

H5 = Height with fastenings, NEMA 1 connection box and hood

W = Width

D = Depth





# Cooling

#### Cooling

ACS320 is fitted with cooling fans as standard. The cooling air must be free from corrosive substances and must not be above the maximum ambient temperature of 50  $^{\circ}$ C.

For more specific limits see the Technical data - Environmental limits in this catalogue.

## Cooling air flow

Type designation	Frame	Heat dis	ssipation	Air flow		
	size	[W]	BTU/hr¹)	m³/h	ft³/min	
I-phase AC supply, 200	to 240 V					
ACS320-01U-02A4-2	R0	42	142	-	-	
ACS320-01U-04A7-2	R1	64	220	24	14	
ACS320-01U-06A7-2	R1	86	295	24	14	
ACS320-01U-07A5-2	R2	90	306	21	12	
ACS320-01U-09A8-2	R2	111	377	21	12	
3-phase AC supply, 200	to 240 V					
ACS320-03U-02A6-2	R0	42	142	-	-	
ACS320-03U-03A9-2	R0	54	183	-	-	
ACS320-03U-05A2-2	R1	64	220	24	14	
ACS320-03U-07A4-2	R1	86	295	24	14	
ACS320-03U-08A3-2	R1	88	302	21	12	
ACS320-03U-10A8-2	R2	111	377	21	12	
ACS320-03U-14A6-2	R2	140	476	52	31	
ACS320-03U-19A4-2	R2	180	613	52	31	
ACS320-03U-26A8-2	R3	285	975	71	42	
ACS320-03U-34A1-2	R4	328	1119	96	57	
ACS320-03U-50A8-2	R4	488	1666	96	57	
B-phase supply voltage	380 - 480	V units				
ACS320-03U-01A2-4	R0	35	121	-	-	
ACS320-03U-01A9-4	R0	40	138	-	-	
ACS320-03U-02A4-4	R1	50	170	13	8	
ACS320-03U-03A3-4	R1	60	204	13	8	
ACS320-03U-04A1-4	R1	69	235	13	8	
ACS320-03U-05A6-4	R1	90	306	19	11	
ACS320-03U-07A3-4	R1	107	364	24	14	
ACS320-03U-08A8-4	R1	127	433	24	14	
ACS320-03U-12A5-4	R3	161	551	52	31	
ACS320-03U-15A6-4	R3	204	697	52	31	
ACS320-03U-23A1-4	R3	301	1029	71	42	
ACS320-03U-31A0-4	R4	408	1393	96	57	
ACS320-03U-38A0-4	R4	498	1700	96	57	
ACS320-03U-44A0-4	R4	588	2007	96	57	

### Free space requirements

Enclosure type	Space above	Space below	Space on left/right		
	in	in	in		
All frame sizes	2.95	2.95	0		

<sup>1)</sup> BTU/hr = British Thermal Unit per hour. BTU/hr is approximately 0.293 Watts.

 $<sup>^{\</sup>mbox{\tiny 2)}}$  Frame size R0 with free convection cooling.

# Circuit protection

## Circuit protection

Standard fuses can be used with ABB general purpose drives. For input fuse connections see table below.







## Selection table

Type designation	IEC fuses		UL fuses	Manual motor protector						
	size	[A]	Fuse type <sup>1)</sup>	UL Class T or CC (600 V) [A]	MMP type code <sup>3) 4)</sup>	Trip current setting [A]				
1-phase AC supply, 2	00 to 24	0 V								
ACS320-01U-02A4-2	R0	10	gG	10	MS132-6.3 & S1-M3-25 5)	6.1				
ACS320-01U-04A7-2	R1	16	gG	20	MS451-16E	11.4				
ACS320-01U-06A7-2	R1	16/20 <sup>2)</sup>	gG	25	MS451-20E	16.1				
ACS320-01U-07A5-2	R2	20/25 2)	gG	30	MS451-20E	16.8				
ACS320-01U-09A8-2	R2	25/35 <sup>2)</sup>	gG	35	MS451-25E	21.0				
3-phase AC supply, 200 to 240 V										
ACS320-03U-02A6-2	R0	10	gG	10	MS132-6.3 & S1-M3-25 5)	4.7				
ACS320-03U-03A9-2	R0	10	gG	10	MS132-10 & S1-M3-25 <sup>5)</sup>	6.7				
ACS320-03U-05A2-2	R1	10	gG	15	MS132-10 & S1-M3-25 5)	8.4				
ACS320-03U-07A4-2	R1	16	gG	15	MS451-16E	13.0				
ACS320-03U-08A3-2	R1	16	gG	15	MS451-16E	13.2				
ACS320-03U-10A8-2	R2	16	gG	20	MS451-20E	15.7				
ACS320-03U-14A6-2	R2	25	gG	30	MS451-25E	23.9				
ACS320-03U-19A4-2	R2	25	gG	35	MS451-32E	27.3				
ACS320-03U-26A8-2	R3	63	gG	60	MS451-50E	45.0				
ACS320-03U-34A1-2	R4	80	gG	80	MS495-63E	55.0				
ACS320-03U-50A8-2	R4	100	gG	100	MS495-90E	76.0				
3-phase AC supply, 4	40 to 48	80 V <sup>6)</sup>	•							
ACS320-03U-01A3-4	R0	10	gG	10	MS132-2.5 & S1-M3-25 5)	2.0				
ACS320-03U-02A1-4	R0	10	gG	10	MS132-4.0 & S1-M3-25 5)	3.3				
ACS320-03U-02A6-4	R1	10	gG	10	MS132-6.3 & S1-M3-25 5)	3.8				
ACS320-03U-03A6-4	R1	10	gG	10	MS132-6.3 & S1-M3-25 5)	5.5				
ACS320-03U-04A5-4	R1	16	gG	15	MS132-10 & S1-M3-25 5)	6.3				
ACS320-03U-06A2-4	R1	16	gG	15	MS132-10 & S1-M3-25 5)	8.8				
ACS320-03U-08A0-4	R1	16	gG	20	MS451-16E	11.0				
ACS320-03U-09A7-4	R1	20	gG	25	MS451-16E	12.0				
ACS320-03U-13A8-4	R3	25	gG	30	MS451-20E	17.0				
ACS320-03U-17A2-4	R3	35	gG	35	MS451-25E	20.0				
ACS320-03U-25A4-4	R3	50	gG	50	MS451-32E	28.0				
ACS320-03U-34A1-4	R4	80	gG	80	MS451-50E	48.0				
ACS320-03U-41A8-4	R4	100	gG	100	MS495-63E	56.0				
ACS320-03U-48A4-4	R4	100	gG	100	MS495-63E	61.0				

Other fuse types can be used if they meet the ratings and the melting curve of the fuse does not exceed the melting curve of the fuse mentioned in this

- 1) According to IEC-60269 standard.
- $^{\scriptscriptstyle 2)}$  If 50% overload capacity is needed, use the bigger fuse alternative.
- 3) All manual motor protectors listed are Type E self-protected up to 65 kA.
- 4) Manual motor protectors may require adjusting the trip limit from the factory setting at or above the drive input Amps to avoid nuisance tripping. If the manual motor protector is set to the maximum current trip level and nuisance tripping is occurring, then select the next size MMP. (MS132-10 is the highest size in MS132 frame size to meet Type E at 65 kA; the next size up is the MS451-16E).
- <sup>5)</sup> S1-M3-25 line side feeder terminal is needed with manual motor protector to meet Type E self protection class according to UL and cUL requirements.
- 6) 480Y/277V only.

## Control connections

ACS320 - 0XU - XXXX - 2 + XXXX

#### **Application macros**

Application macros are preprogrammed parameter sets. While starting up the drive, the user typically selects one of the macros that is best suited for the application. The diagram below gives an overview of ACS320 control connections and shows the default I/O connections for the HVAC default macro.

HVAC default
 Internal timer

Supply fan
 Internal timer / constant speeds

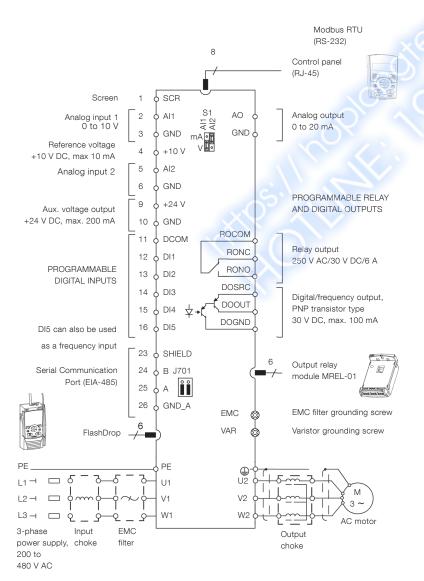
Return fanFloating pointCooling tower fanDual setpoint PID

CondenserDual setpoint PID / constant

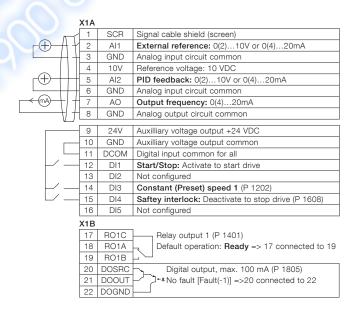
Booster pump speedsPump alternation - E-BypassHand control

In addition to the standard macros the user can create two user macros. The user macro allows the user to save the parameter settings for later use.

The diagram below gives an overview of ACS320 control connections. Please refer to the ACS320 user's manual for more detailed information.



## Typical I/O connections



# **Options**

ACS320	-	0XU	-	XXXX	_	2	+	XXXX
--------	---	-----	---	------	---	---	---	------

### How to select options

The options shown in the table below are available within the ACS320 range. The control panels have an associated 4-figure option code, which is shown in the second column. It is this code that replaces XXXX in the type code above.

Options	Ordering code	Description	Model
Protection class	*)	NEMA 1/UL type 1 (R0, R1, R2)	MUL1-R1
	*)	NEMA 1/UL type 1 (R3)	MUL1-R3
	")	NEMA 1/UL type 1 (R4)	MUL1-R4
Control panel	J400	Advanced control panel	ACH-CP-B
	J404	Basic control panel	ACS-CP-C
Panel mounting kit	*)	Panel mounting kit	ACS/H-CP-EXT
	*)	Panel holder mounting kit	OPMP-01
Extension modules	L511	Relay output extension module.	MREL-01
Tools	")	FlashDrop tool	MFDT-01
	")	DriveWindow Light 2	DriveWindow Light 2
Remote monitoring	ຳ	Ethernet adapter	SREA-01

<sup>&</sup>quot;) Ordering with a separate MRP code number. With MUL1 option, suitable for installation in a compartment handling conditioned air.

<sup>1)</sup> The ACS320 is compatible with ACS-CP-C basic control panel Rev M or later.

<sup>&</sup>lt;sup>2)</sup> The ACS320 is compatible with ACH-CP-B assistant control panel Rev E or later. (New panel series manufactured since 2007 with serial number XYYWWRXXXX, where year Y = 7 or greater and revision R = E, F, G, ...)

# **Options** User interfaces

ACS320 0XU XXXX **XXXX** 

#### User interface

#### Panel cover

The purpose of the panel cover is to protect the drive's connection surfaces. The ACS320 drive is delivered with a panel cover as standard. In addition there are two alternative control panels available as options.

### Basic control panel

The basic control panel features a single line numeric display. The panel can be used to control the drive, set parameter values or copy them from one drive to another.

#### Advanced control panel

The ACS320 operator control panel is designed specifically for HVAC applications. The operator panel includes HAND, OFF, AUTO, and speed INCREASE and DECREASE keys for manual operation. Other features include a HELP key, backlit display, multilingual selections, text / graphic displays and a real time clock. The large display and soft keys make it extremely easy to navigate.

#### Panel mounting kits

To attach the control panel to the outside of a larger enclosure, two panel mounting kits are available. A simple and costefficient installation is possible with the ACS/H-CP-EXT kit, while the OPMP-01 kit provides a more user-friendly solution, including a panel platform that enables the panel to be removed in the same way as a drive-mounted panel. The panel mounting kits include all hardware required, including 3 meters extension cables and installation instructions.

### Protection and installation

#### **NEMA 1 kit**

The NEMA 1 kit includes a connection box for finger protection, conduit tube installation, and a hood for protection against dirt and dust.

#### Terminal cover

The terminal cover is for protection of the I/O connections.

#### Clamping plates

The clamping plates are used for protection against electrical disturbances. The clamping plates with the clamps are included in the drive package as standard.



Panel cover (included as standard)





Advanced control panel



Panel holder mounting kit OPMP-01



NFMA 1 kit



Terminal cover (included as standard)



Clamping plates (included as standard)

# **Options** User interfaces

ACS320 0XU **XXXX** XXXX

#### Serial communication

The embedded building automation protocols bring connectivity to major HVAC systems. A single twisted pair cable avoids large amounts of conventional cabling, thereby reducing costs and increasing system reliability.

#### Extension module

#### MREL-01

ACS320 has one relay output as standard. The optional MREL-01 module offers three additional relay outputs. The outputs can be configured for different functions by setting selected parameters.

#### SREA-01 Ethernet adapter

SREA-01 Ethernet adapter with remote monitoring access can send process data, data logs and event messages independently, without a PLC or a dedicated on-site computer. It has an internal web server for configuration and drive access.

In remote locations without qualified service people on-site it is vital to be able to monitor the drive remotely. Monitoring and diagnostics routines can be easily implemented with ABB's remote monitoring tool. The remote monitoring tool enables to connect multiple drives to Ethernet, to collect operational data from the process and send the collected data to a central location for process monitoring and further analysis.

Additionally, the SREA-01 Ethernet adapter offers Modbus TCP to Modbus RTU gateway functionality which enables Modbus TCP connectivity to ACS320. Please refer to SREA-01 user's guide for more detailed information.







Extension module MREL-01

SREA-01 Ethernet adapter

# Options Software tools

A separate order line and type designation is required for any of these software tool options.

#### **DriveWindow Light**

DriveWindow Light is an easy-to-use startup and maintenance tool for ACS320 drives. It can be used in an offline mode, which enables parameter setting at the office even before going to the actual site. The parameter browser enables viewing, editing and saving of parameters. The parameter comparison feature makes it possible to compare parameter values between the drive and saved parameter files. With the parameter subset you can create your own parameter sets. Controlling the drive is one of the features in DriveWindow Light. With this software tool, you can monitor up to four signals simultaneously. This can be done in both graphical and numerical format. DriveWindow Light version 2.9 or later is compatible with ACS320 drives.

#### Startup wizards

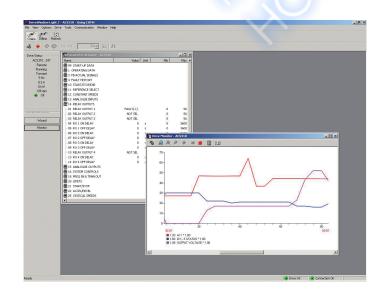
Startup wizards make the setting of parameters easy. Simply launch the wizard, select an appropriate assistant eg, for setting analog outputs, and all parameters related to this function are shown together with help pictures.

#### **Highlights**

- Editing, saving and downloading parameters
- Graphical and numerical signal monitoring
- Drive control
- Startup wizards

#### **DriveWindow Light requirements**

- Windows NT/2000/XP/Vista/Windows 7
- Serial port from a PC
- Control panel connector



# Options External

A separate order line and type designation is required for any of these external options.

#### FlashDrop tool

FlashDrop is a powerful palm sized tool for fast and easy parameter selecting and setting. It gives the possibility to hide selected parameters to protect the machine. Only the parameters needed in the application are shown. The tool can copy parameters between two drives or between a PC and a drive. All the above can be done without a power connection to the drive – in fact, it is not even necessary to unpack the drive.

#### **DrivePM**

DrivePM (Drive parameter manager) is a tool to create, edit and copy parameter sets for FlashDrop. For each parameter/group the user has a possibility to hide it, which means that the drive user does not see the parameter/group at all. DrivePM version 1.2 is compatible with ACS320 drives.

#### **DrivePM requirements**

- Windows 2000/XP/Vista/Windows 7
- Serial port from a PC

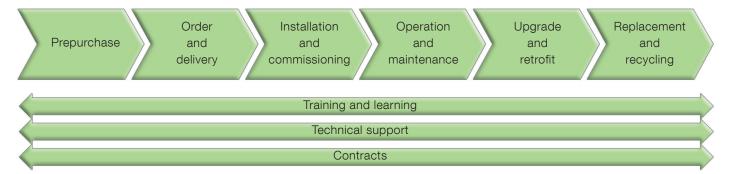
### FlashDrop package includes

- FlashDrop tool
- DrivePM software on a CD-rom
- User's manual in English and in pdf-format on the CD-rom
- Cable OPCA-02 for connection between the PC and FlashDrop tool
- Battery charger



FlashDrop tool

# Expertise at every stage of the value chain



Whether you operate in industry, commerce or a utility your aims remain the same: to keep your motor-driven applications running consistently and efficiently. The life cycle services for ABB drives can help you achieve these aims by maximizing the uptime of your process while ensuring the optimum lifetime of ABB drives in a predictable, safe and low-cost manner.

The life cycle services for ABB drives span the entire value

chain, from the moment you make the first enquiry about a drive through to its disposal and recycling. Throughout the value chain, ABB provides training and learning, technical support and contracts. All of this is supported by one of the most extensive global drive sales and service networks.

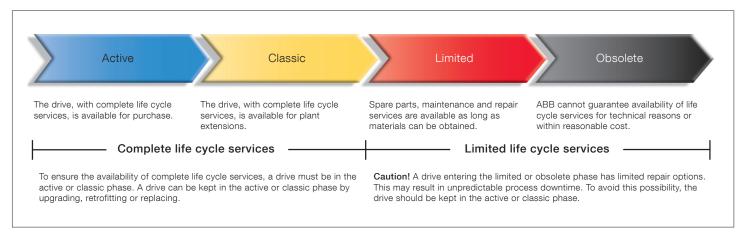
# Secure uptime throughout the drive life cycle

ABB follows a four-phase model for the life cycle management of its drives. The life cycle phases are active, classic, limited and obsolete. Within each phase, every drive series has a defined set of services.

The four-phase drive life cycle management model provides

you with a transparent method for managing your investment in drives. In each phase, you clearly see what life cycle services are available, and more importantly, what services are not available. Decisions on upgrading, retrofitting or replacing drives can be made with confidence.

#### ABB drive life cycle management model





For more information please contact your local ABB representative or visit:

www.abb.com/drives

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