

Shaft Type Ø50mm Multi-turn Absolute Rotary Encoder

■ Features

- Total 23-bit resolution (8388608-division) of 10-bit single-turn (1024-division) and 13-bit multi-turn (8192-revolution)
- Compact size of Ø50mm
- Parallel data/SSI data transmission type
- Easy zero adjustment using single-turn/multi-turn data separated reset function
- Memorizing revolution data up to $\pm 90^\circ$ after blackout without memory back up function
- Possible CW/CCW direction setting with direction function
- Maximizing users convenience with clear, over flow alarm (OVF) function
- Protection structure IP64 (IEC standard) (dust-proof, oil-proof)
- Provides Latch function (parallel output model only)

■ Applications

- Precision machine tool, Fabric machinery, Robot, Parking system

⚠ Please read "Safety Considerations" in the instruction manual before using.



Radial cable type



Axial cable type

■ Ordering Information

| EPM50S | 8 | 10 | 13 | B | PN | 24 | |
|---------------------|----------------|---------------------------|-----------------------------|-------------|---|-------------------|---|
| Series | Shaft diameter | Single-turn | Multi-turn | Output code | Control output | Power supply | Cable |
| Ø50mm Shaft type | Ø8mm | 10-bit (1024-division) | 13-bit (8192-revolution) | Binary code | PN: Parallel NPN open collector output S: SSI Line driver output | 12-24VDC \pm 5% | No mark: Axial cable type S: Radial cable type |

■ Specifications

| Type | | | Shaft Type Ø50mm Multi-turn Absolute Rotary Encoder | | | |
|---------------------------------|-------------------------|----------------------------|--|--|--|--|
| Model | | | EPM50S8-1013-B-S-24-□ | EPM50S8-1013-B-PN-24-□ | | |
| Resolution | Single-turn | 1024-division (10-bit) | | | | |
| | Multi-turn | 8192-revolution (13-bit) | | | | |
| Rotation limit when power off※1 | | | ±90° | | | |
| Electrical specification | Output | Output code | 24-bit, Binary code | | Binary code | |
| | | Control output | SSI (Synchronous Serial Interface) Line driver [Low] - Sink current: max. 20mA, Residual voltage: max. 0.5VDC≐ [High] - Sink current: max. -20mA, Output voltage: min. 2.5VDC≐ | | Parallel NPN open collector output Sink current: max. 32mA, Residual voltage: max. 1VDC≐ | |
| | | Output signal | Single-turn data, multi-turn count, over flow alarm (OVF)※2 | | | |
| | | Output logic | — | | Negative logic output | |
| | | Response time (rise, fall) | — | | Max. 1μs (cable: 2m, I sink = 32mA) | |
| | | Input | Input signal | Single-turn data reset ※3, Multi-turn count reset ※4, Direction, Clear | | |
| | Input level | | 0-1VDC≐ | | | |
| | Input logic | | Low Active, Open or High for common use | | | |
| | Input time | | Single-turn data reset※3, Multi-turn count reset※4, Direction, Clear: approx. over 100ms | | | |
| | | | — | | | Latch: approx. over 500μs |
| | SSI clock input | | Input level | 5VDC≐ ±5% | | — |
| | | | Input frequency | 100kHz to 1MHz | | |
| | Max. response frequency | | | — | | 50kHz |
| | Power supply | | | 12-24VDC≐ ±5% (ripple P-P: max. 5%) | | |
| | Current consumption | | | Max. 150mA (disconnection of the load) | | Max. 100mA (disconnection of the load) |
| | Insulation resistance | | | Over 100MΩ (at 500VDC megger between all terminals and case) | | |
| | Dielectric strength | | | 750VAC 50/60Hz for 1 min (between all terminals and case) | | |
| Connection | | | Axial/Radial cable type (cable gland) | | | |

※1: It calibrates the multi-turn counts by comparing single-turn data before/after power off without counting multi-turn counts when power is off. It shall be used on the condition that no overrated revolution occurred since proper multi-turn data may not be available if any revolutions occurred over $\pm 90^\circ$ from the position when power is off.

※2: OVF alarm is ON when multi-turn count is out of counting range (0 to 8191 revolutions).

※3: Single-turn data will be reset as 「0」 when single-turn data reset is input.

※4: Multi-turn count will be reset as 「0 revolution」 when multi-turn count reset is input.

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/Connector Cables/Sensor Distribution Boxes/ Sockets

Specifications

| | | | |
|--------------------------|--|--|--|
| Type | | Shaft Type Ø50mm Multi-turn Absolute Rotary Encoder | |
| Model | | EPM50S8-1013-B-S-24-□ | EPM50S8-1013-B-PN-24-□ |
| Mechanical specification | Starting torque | Max. 70gf·cm (0.0069N·m) | |
| | Moment of inertia | Max. 40g·cm ² (4×10 ⁻⁶ kg·m ²) | |
| | Shaft loading | Radial: max. 10kgf, Thrust: max. 2.5kgf | |
| | Max. allowable revolution ^{※5} | 3,000rpm | |
| Vibration | | 1.5mm amplitude at frequency of 10 to 55Hz (for 1 min) in each X, Y, Z direction for 2 hours | |
| Shock | | Approx. max. 50G | |
| Environment | Ambient temp. | -10 to 70°C, storage: -25 to 85°C | |
| | Ambient humi. | 35 to 85%RH, storage: 35 to 90%RH | |
| Protection structure | | Axial cable type: IP64 (IEC standard), Radial cable type: IP50 (IEC standard) | |
| Cable | Ø6mm, 10-wire, 2m, Shield cable (AWG28, core diameter: 0.08mm, number of cores: 19, insulation out diameter: Ø0.8mm) | | Ø6mm, 17-wire×2, 2m, Shield cable (AWG28, core diameter: 0.08mm, number of cores: 17, insulation out diameter: Ø0.8mm) |
| Accessory | | Bracket, coupling | |
| Approval | | CE | |
| Weight ^{※6} | | Approx. 409g (approx. 324g) | Approx. 560g (approx. 475g) |

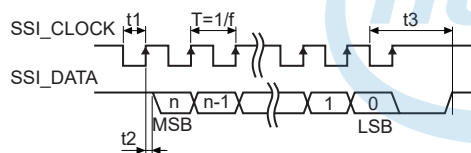
※5: In case of Parallel type model, Make sure that Max. response revolution should be lower than or equal to max. allowable revolution when selecting the resolution.

$$[\text{Max. response revolution (rpm)}] = \frac{\text{Max. response frequency}}{\text{Resolution}} \times 60 \text{ sec}$$

※6: The weight includes packaging. The weight in parenthesis is for unit only.

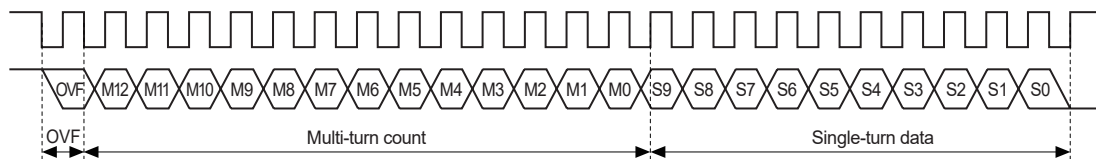
※Environment resistance is rated at no freezing or condensation.

Synchronous Serial Interface (SSI) Output Timing Diagram



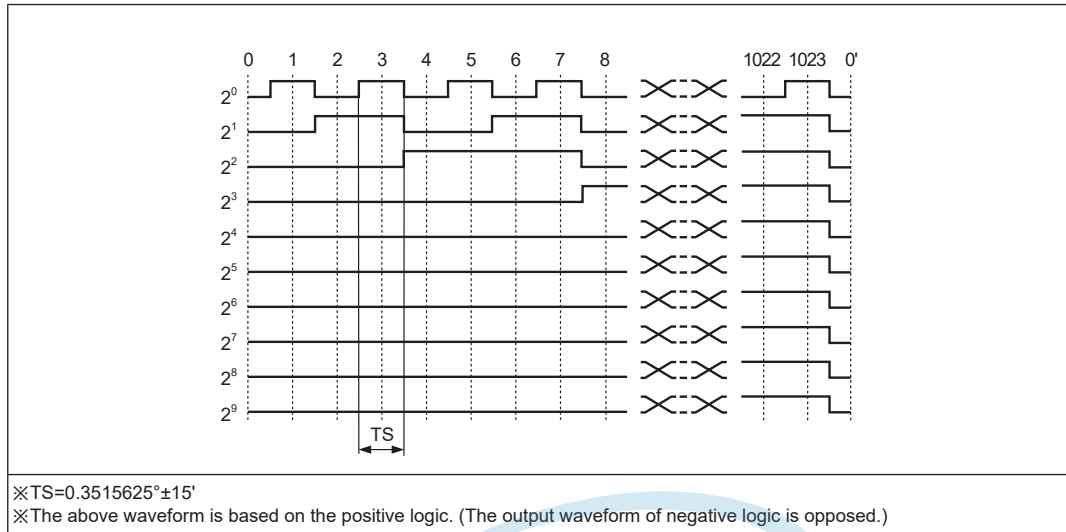
| | |
|-------------------|------------------|
| Clock Frequency f | 100kHz to 1MHz |
| T | T: 1 to 10μs |
| Time lag t2 | 0.5μs < t1 < 5μs |
| Monoflop Time t3 | t2 < 0.3μs |
| | 15μs < t3 < 30μs |

Synchronous Serial Interface (SSI) Data Output

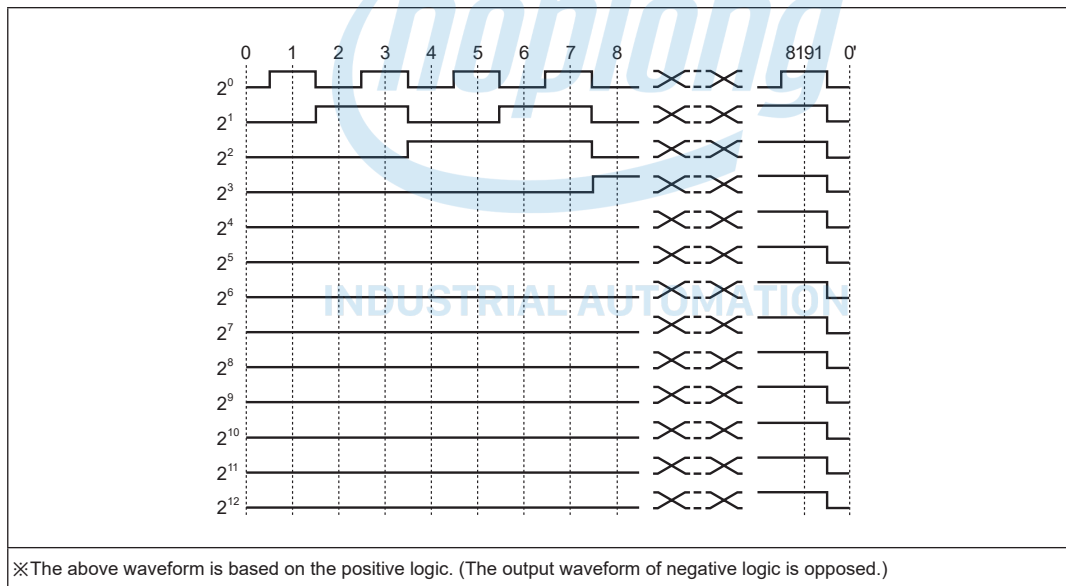


| Clock input bit | Data output name | Data output bit | Clock input bit | Data output name | Data output bit |
|-----------------|---------------------|-----------------|-----------------|------------------|-----------------|
| 1 | Over flow alarm bit | 0-bit | 15 | Single-turn data | 9-bit (MSB) |
| 2 | Multi-turn count | 12-bit (MSB) | 16 | | 8-bit |
| 3 | | 11-bit | 17 | | 7-bit |
| 4 | | 10-bit | 18 | | 6-bit |
| 5 | | 9-bit | 19 | | 5-bit |
| 6 | | 8-bit | 20 | | 4-bit |
| 7 | | 7-bit | 21 | | 3-bit |
| 8 | | 6-bit | 22 | | 2-bit |
| 9 | | 5-bit | 23 | | 1-bit |
| 10 | | 4-bit | 24 | | 0-bit (LSB) |
| 11 | | 3-bit | | | |
| 12 | | 2-bit | | | |
| 13 | | 1-bit | | | |
| 14 | | 0-bit (LSB) | | | |

■ Parallel Interface 1024-Division Single-turn Data Output Waveform

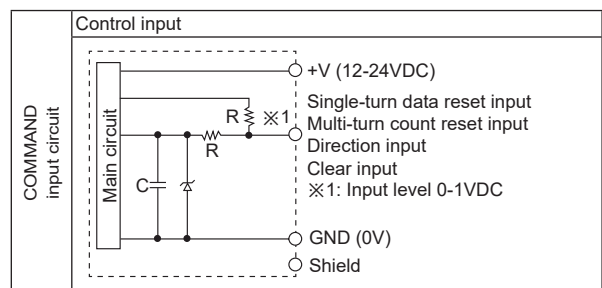
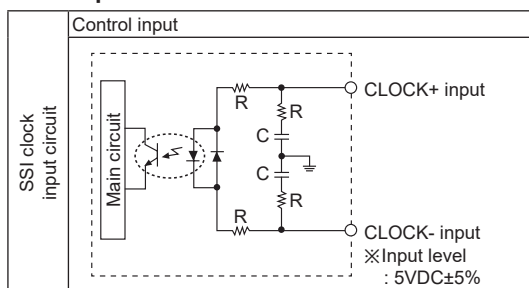


■ Parallel Interface 8192-Revolution Multi-turn Count Data Output Waveform



■ Control Output I/O Circuit

• SSI input



SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

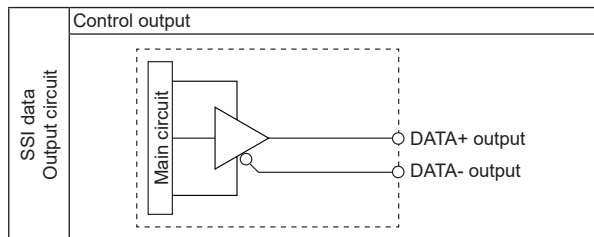
(G) Pressure Sensors

(H) Rotary Encoders

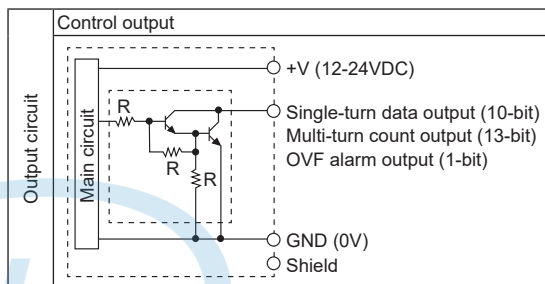
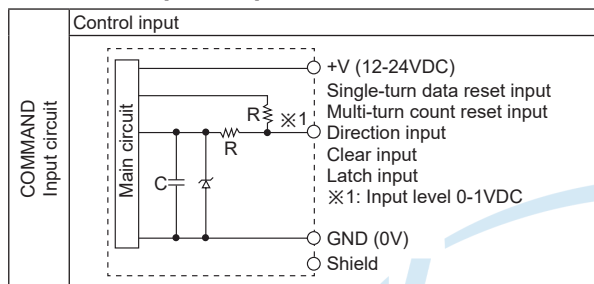
(I) Connectors/
Connector Cables/
Sensor Distribution
Boxes/ Sockets

■ Control Output I/O Circuit

○ SSI output



○ Parallel input/output



※Each bit of output has the same circuit.

※Please be aware of the fact that overload and short circuit may cause circuit break.

■ Connections

○ SSI Line driver output type

| Cable | | | Cable | | |
|-------------|---------------|--------|-------------|----------------------------|------------------------|
| Cable color | Description | | Cable color | Description | |
| Brown | SSI | CLOCK+ | Gray | COMMAND | Single-turn data reset |
| Red | | CLOCK- | Blue | | Multi-turn count reset |
| Orange | | DATA+ | Green | | Direction |
| Yellow | | DATA- | Purple | | Clear |
| White | +V (12-24VDC) | | Shield | Signal shield cable (F.G.) | |
| Black | GND (0V) | | — | | |

○ Parallel NPN open collector output type

| Multi-turn count cable (sheath color: black) | | |
|--|----------------------------|-----------------|
| Cable color | Description | |
| Brown | Multi-turn count | 2 ⁰ |
| Red | | 2 ¹ |
| Orange | | 2 ² |
| Yellow | | 2 ³ |
| Green | | 2 ⁴ |
| Blue | | 2 ⁵ |
| Purple | | 2 ⁶ |
| Gray | | 2 ⁷ |
| Pink | | 2 ⁸ |
| Clear | | 2 ⁹ |
| Light brown | | 2 ¹⁰ |
| Light yellow | | 2 ¹¹ |
| Light green | | 2 ¹² |
| Light blue | OVF | |
| Light purple | Multi-turn count reset | |
| White | +V (12-24VDC) | |
| Black | GND (0V) | |
| Shield | Signal shield cable (F.G.) | |

| Single-turn data cable (sheath color: gray) | | |
|---|----------------------------|----------------|
| Cable color | Description | |
| Brown | Single-turn data | 2 ⁰ |
| Red | | 2 ¹ |
| Orange | | 2 ² |
| Yellow | | 2 ³ |
| Green | | 2 ⁴ |
| Blue | | 2 ⁵ |
| Purple | | 2 ⁶ |
| Gray | | 2 ⁷ |
| Pink | | 2 ⁸ |
| Clear | | 2 ⁹ |
| Light brown | N.C. | |
| Light yellow | Direction | |
| Light green | Latch | |
| Light blue | Clear | |
| Light purple | Single-turn data reset | |
| White | +V (12-24VDC) | |
| Black | GND (0V) | |
| Shield | Signal shield cable (F.G.) | |

※Unused wires must be insulated.

※Do the wiring properly.

※Encoder metal case and shield cable must be grounded (F.G.).

※Please use caution to avoid short circuit when connecting output cables because I/O circuit uses the dedicated driver IC.

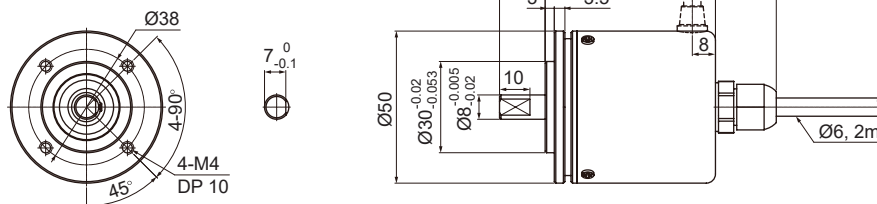
※As for Parallel output, it is recommended to connect +V and GND of both multi-turn count cable and single-turn data cable.

※Do not apply tensile strength over 30N to the cable.

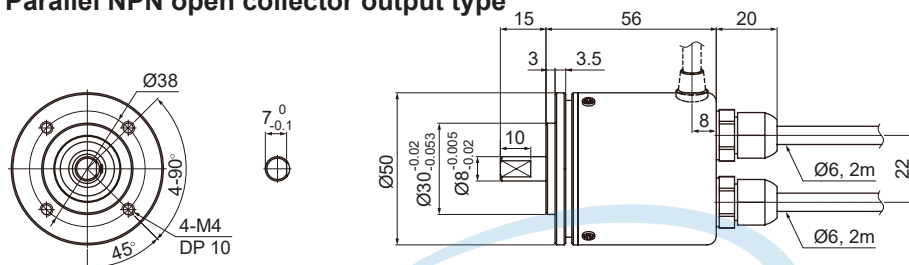
■ Dimensions

(unit: mm)

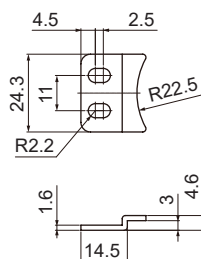
◎ SSI Line driver output type



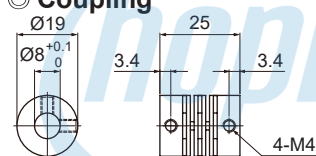
◎ Parallel NPN open collector output type



◎ Bracket



◎ Coupling



- Parallel misalignment: max. 0.25mm
- Angular misalignment: max. 5°
- End-play: max. 0.5mm

- ※ Do not load overweight on the shaft.
- ※ Do not put strong impact when insert a coupling into shaft.
Failure to follow this instruction may result in product damage.
- ※ Fix the unit or a coupling by a wrench under 0.15N·m of torque.
- ※ When you install this unit, if eccentricity and deflection angle are larger, it may shorten the life cycle of this unit.
- ※ For parallel misalignment, angular misalignment, end-play terms, refer to the "Glossary" section of Technical Description.
- ※ For flexible coupling (ERB series) information, refer to the ERB series section.

■ Functions

◎ Single-turn data reset

Single-turn data will be reset as 「0」 when single-turn data reset cable is inputted 0 to 1V (over 100ms). In case of not using single-turn data reset cable, connect the line to OPEN or + V.

◎ Multi-turn count reset

Multi-turn data will be reset as 「0 revolution」 when multi-turn count reset cable is inputted 0 to 1V (over 100ms). In case of not using multi-turn count reset cable, connect the line to OPEN or + V.

OVF alarm will be reset with multi-turn count reset input.

◎ Direction

Connect the direction cable to OPEN or +V and turn on the power. Output will increase when rotation direction is CW from shaft axis. In case of connecting 0 to 1 V (over 100ms), output will increase when rotation direction is CCW. If direction setting is reset, single-turn data, multi-turn count and OVF will be reset together since direction setting is initial setting which is set with Power ON.

◎ Clear

Single-turn data will be reset as 「0」 and multi-count will be also reset as 「0 revolution」 when clear cable is inputted 0 to 1V (over 100ms). In case of not using clear cable, connect the cable to OPEN or + V. OVF alarm will be reset with clear input.

◎ Latch (parallel output model only)

When the latch cable is inputted 0 to 1V (over 500μs), outputs for single-turn data, multi-turn count and OVF at latch point will be remained. When latch cable is connected to OPEN or +V, output will be returned to operating mode output.

◎ Over flow alarm (OVF)

It is an alarm function when multi-turn count is out of rotation ranges (0 to 8191 revolutions).

Over flow alarm is also reset with multi-turn count value when multi-turn count reset signal is inputted.

SENSORS

CONTROLLERS

MOTION DEVICES

SOFTWARE

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) LIDAR

(D) Door/Area Sensors

(E) Vision Sensors

(F) Proximity Sensors

(G) Pressure Sensors

(H) Rotary Encoders

(I) Connectors/ Connector Cables/ Sensor Distribution Boxes/ Sockets