


■ Features

-  Please read "Caution for your safety" in operation manual before using.



- Stepper motor, Servo motor, Precision motor, high-precision encoder, dynamometer driver, high speed/precision position control system

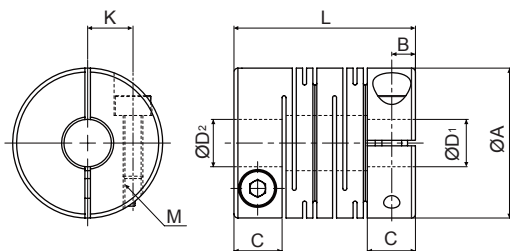
ERB	A	-	19	C	-	d₁/d₂
Item				Bore diameters	Number/Number	Bore diameters
				Connection type	S	Set screw
					C	Clamp
				External diameter	Number	External diameter (mm)
	Type	A	Double beam (Normal Type)			
		ERB	Radial beam type coupling			

Model		ERB-A-19C-□	ERB-A-19S-□	ERB-A-26C-□	ERB-A-26S-□
Connection type		Clamp	Set screw	Clamp	Set screw
Max. revolutions		8000rpm	20000rpm	6000rpm	15000 rpm
Max. torque		1.2 N·m (12.17 kgf·cm)		3.0 N·m (30.42 kgf·cm)	
Rated torque		0.6 N·m (6.08 kgf·cm)		1.5 N·m (15.21 kgf·cm)	
Mounting bolt (Mounting torque)		M2.5 (1N·m)	M3 (0.7N·m)	M3 (0.7N·m)	M4 (1.7N·m)
Torsional stiffness		140 N·m/rad		240 N·m/rad	
Moment of inertia		6.4×10 ⁻⁷ kg·m ²		3.4×10 ⁻⁶ kg·m ²	
Max. allowable misalign- ment	Angular misalignment	2.5°			
	Parallel misalignment	0.15mm		0.2mm	
	End-play	±0.3mm		±0.4mm	
Standard bore diameter (tolerance h7)		Ø4, Ø5, Ø6mm		Ø6, Ø8mm	
Min. allowable bore diameter		Ø4mm		Ø5mm	
Max. allowable bore diameter		Ø8mm		Ø12mm	
Material		Aluminum (AL 7075-T6), Alumite surface			
Unit weight		Approx. 12g		Approx. 33g	

■ Dimensions

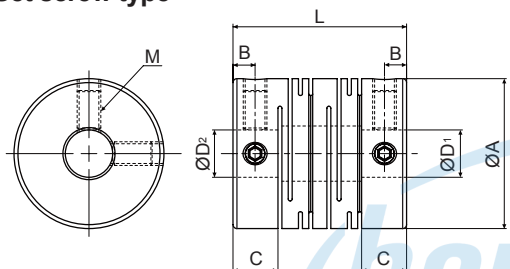
◎ Clamp type

(unit: mm)



Model	ØA	L	ØD ₁	ØD ₂	M	C	B	K
ERB-A-19C-04/04	19	23	4 ^{+0.018} ₀	4 ^{+0.018} ₀	M2.5	6.1	3	5.75
ERB-A-19C-04/05				5 ^{+0.018} ₀				
ERB-A-19C-04/06				6 ^{+0.018} ₀				
ERB-A-19C-05/05			5 ^{+0.018} ₀	5 ^{+0.018} ₀				
ERB-A-19C-05/06				6 ^{+0.018} ₀				
ERB-A-19C-06/06				6 ^{+0.018} ₀				
ERB-A-26C-06/06	26	31.4	6 ^{+0.018} ₀	6 ^{+0.018} ₀	M3	7.4	3.7	8.55
ERB-A-26C-06/08			8 ^{+0.018} ₀	8 ^{+0.018} ₀				
ERB-A-26C-08/08				8 ^{+0.018} ₀				

◎ Set screw type



Model	ØA	L	ØD ₁	ØD ₂	M	C	B
ERB-A-19S-04/04	19	22	4 ^{+0.018} ₀	4 ^{+0.018} ₀	M3	5.7	2.8
ERB-A-19S-04/05				5 ^{+0.018} ₀			
ERB-A-19S-04/06				6 ^{+0.018} ₀			
ERB-A-19S-05/05			5 ^{+0.018} ₀	5 ^{+0.018} ₀			
ERB-A-19S-05/06				6 ^{+0.018} ₀			
ERB-A-19S-06/06				6 ^{+0.018} ₀			
ERB-A-26S-06/06	26	30	6 ^{+0.018} ₀	6 ^{+0.018} ₀	M4	6.8	3.4
ERB-A-26S-06/08			8 ^{+0.018} ₀	8 ^{+0.018} ₀			
ERB-A-26S-08/08				8 ^{+0.018} ₀			

■ Proper Usage

The flexible coupling is available in the places where vibration or misalignment occurs. It must be used within the rated allowable misalignment range.

When using the flexible coupling over the rated misalignment range, it may cause vibration or shorten the life cycle.

When there are more than two misalignments, each allowable value is 50%.

It is recommended to use the flexible coupling below 1/3 of the allowable misalignment value to extend the life of the coupling and the applied equipment.

- This product is for transferring rotation power. If there is a risk of human contact, attach the caution label or install a safety cover in a prominent position.
- Rated torque is available to transfer the power continuously. Check the rated capacity before using this product.
- Max. torque is available to transfer the power in a moment. Check the rated capacity before using this product.

◎ Caution for using

- Couplings are for transferring rotation angle and power between shafts. Before using this, make sure to check the purpose and appropriacy.
- This product uses high strength aluminum alloy and has spring power as Radial beam type. However, if the coupling is dropped, hit or applied excessive power, it may be damaged or transformed.
- If the coupling is applied over the rated misalignment, or the tolerance of the shaft is over the allowable value, it may cause plastic deformation, damage of the product or shorten the life cycle.
- When it occurs abnormal sound during operating the equipment with this coupling, stop the operation and remove the cause such as misalignment, unscrewing, or rotation hazard.
- If this coupling is applied to the equipment which has big fluctuation of load, shaft may be loose by unscrewing. Tighten the screw securely and prevent from unscrewing.

(A) Photoelectric Sensors

(B) Fiber Optic Sensors

(C) Door/Area Sensors

(D) Proximity Sensors

(E) Pressure Sensors

(F) Rotary Encoders

(G) Connectors/ Sockets

(H) Temperature Controllers

(I) SSRs / Power Controllers

(J) Counters

(K) Timers

(L) Panel Meters

(M) Tacho / Speed / Pulse Meters

(N) Display Units

(O) Sensor Controllers

(P) Switching Mode Power Supplies

(Q) Stepper Motors & Drivers & Controllers

(R) Graphic/ Logic Panels

(S) Field Network Devices

(T) Software